

# Robot interface module for AX



## OVERVIEW

Fieldbus communication between the power source and robot controller is enabled with different types of modules. The protocol can be chosen based on the customer preference.

The most commonly used is Ethernet IP. KUKA and Beckhoff use Ethercat. Profinet&Profibus is typical for Siemens, and Modbus is being used in Universal Robot. DeviceNet is a typical network protocol in older systems.

## ORDERING CODES

RX 701 1200 – M40 EtherNet/IP RJ45 2  
RX 702 1200 – M40 PROFINET RJ45 2  
RX 703 1200 – M40 EtherCAT RJ45 2  
RX 704 1200 – M40 Modbus TCP RJ45 2  
RX 705 4100 – M40 PROFIBUS D89 1  
RX 706 3100 – M40 DeviceNet 1  
RX 707 2200 – M40 DeviceNet M12 2

## TECHNICAL SPECIFICATIONS

### Robot interface module for AX

Product code

See technical specifications.